

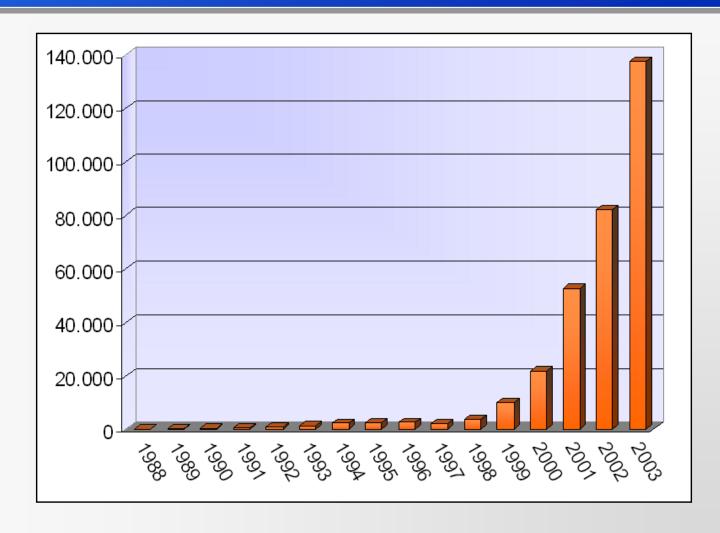
# Detecting Malicious Code by Model Checking

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# Computer Security Incidents

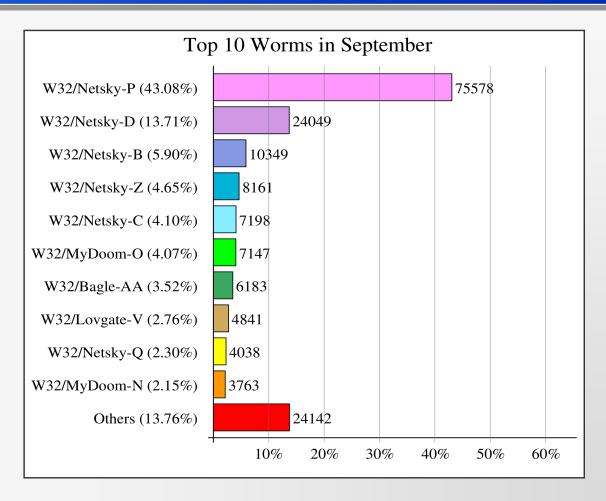




Computer Security Incidents from 1988-2003 (Source: CERT)

#### E-Mail Worms – Prevalence





Computer worms in incoming e-mails at the Department of Computer Science of the TUM in September 2004.

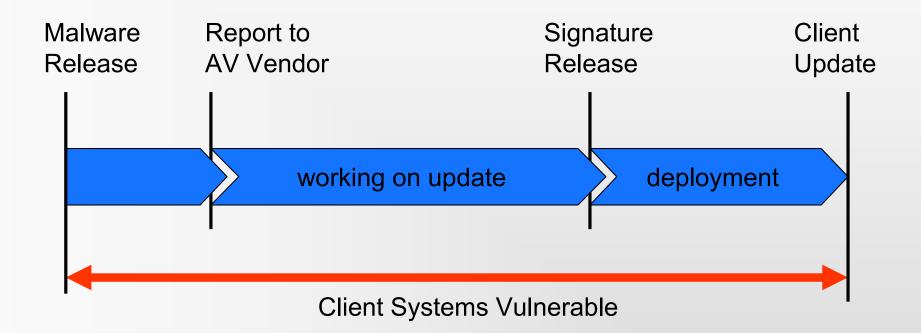
#### E-Mail Worms – Facts



- Predominantly variants of existing worms
  - Currently 200 new threats per month (Symantec)
  - More than 30 variants of NetSky, up to 3 in one day
  - Source code often widely distributed
  - 'Script-Kiddies'
  - Variants differ only slightly in terms of functionality
  - Binary worm code can be highly different (compiler settings, executable packers)
- Timely updates to virus detectors are critical

## Window of Vulnerability





In case of the Sober.C worm, this timespan ranged from 10 hours up to 4 days! (Source: Virus Bulletin, 02/04)

#### **Detection Methods**



- Signature Matching
  - Regular expressions
  - Fast and reliable
  - Not mutation tolerant (Christodorescu, Jha 2003)
- Dynamic Analysis
  - Limited timespan, not all execution paths
  - Useful for monitoring (IDS)
- Static Analysis
  - Verification of possible behavior
  - Relies on disassembly

## Model Checking



- Well proven verification method
- Classically used for verifying properties such as Fairness and Liveness in distributed systems
- Verifies whether a model obeys a specification
  - Models are given as labeled transition systems
  - Specifications are given in temporal logics (e.g. CTL or LTL)

#### **Example for Fairness:**

"Whenever a process requests to enter its critical area, it is eventually allowed to do so"

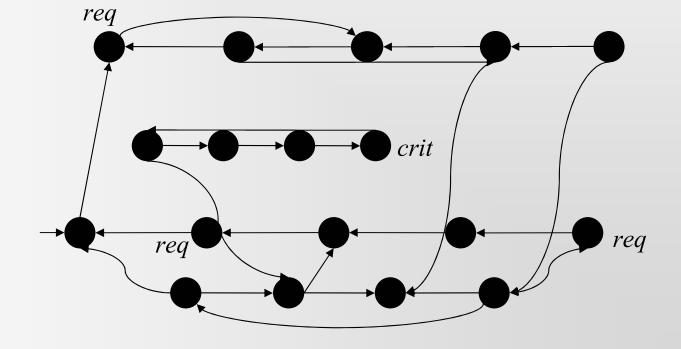
# Model Checking – Example



CTL specification of Fairness:

$$\mathbf{AG}$$
 (req  $\rightarrow \mathbf{AF}$  crit)

Model:

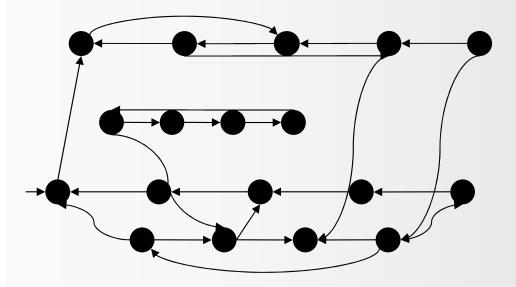


#### Malicious Code Detection



- Specification of malicious behavior
- Model extraction from executable machine code
- Verification by Model Checking

#### Model

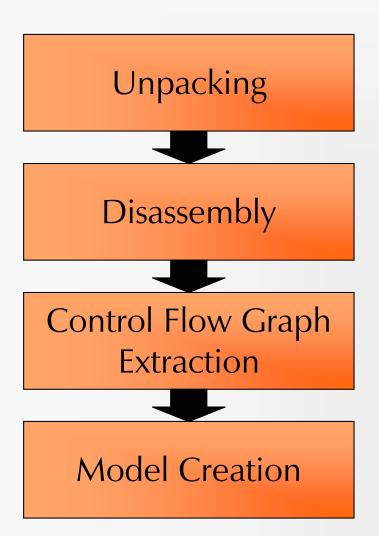


#### Specification

```
\exists L_m \exists L_c \exists v_{File}(
                   \exists r_0 \exists r_1 \exists L_0 \exists L_1 \exists c_0 (
                            \mathbf{EF}(\mathsf{lea}(r_0, v_{File}) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\mathsf{mov}(r_0, t) \lor \mathsf{lea}(r_0, t))) \mathbf{U} \#loc(L_0)) \land
                            \mathbf{EF}(\mathtt{mov}(r_1, 0) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t(\mathtt{mov}(r_1, t) \vee \mathtt{lea}(r_1, t))) \mathbf{U} \# loc(L_1)) \wedge
                            \mathbf{EF}(\operatorname{push}(c_0) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \vee \operatorname{pop}(t)))
                                      \mathbf{U}(\operatorname{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
                                                \mathbf{U}(\operatorname{push}(r_1) \land \#loc(L_1) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
                                                         \mathbf{U}(\texttt{call}(\texttt{GetModuleFileNameA}) \land \#loc(L_m)))))
10.
                   \wedge (\exists r_0 \exists L_0 (
11.
                            \mathbf{EF}(\mathsf{lea}(r_0, v_{File}) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t (\mathsf{mov}(r_0, t) \vee \mathsf{lea}(r_0, t))) \mathbf{U} \# loc(L_0)) \wedge
12.
                            \mathbf{EF}(\operatorname{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
13.
                                      \mathbf{U}(\text{call}(\text{CopyFileA}) \land \#loc(L_c)))
14.
15.
                   \wedge \mathbf{EF}(\#loc(L_m) \wedge \mathbf{EF} \#loc(L_c))
```

#### Model Extraction





- Worms are commonly packed by executable packers (e.g. UPX) and need to be unpacked
- Disassembly transforms an executable byte sequence into a sequence of instructions
- Control flow graphs display conditional branches and loops in the executable
- The graph is annotated with assembler instructions and locations (offsets)

### Model Extraction – Example



```
label1: cmp ebx, [bp-4]
```

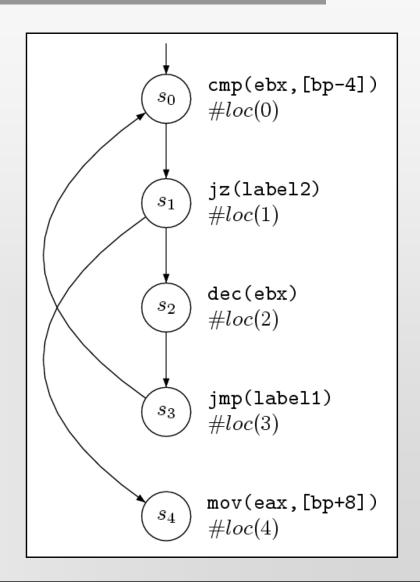
jz label2

dec ebx

jmp label1

label2: mov eax, [bp+8]

. . .



## Model Extraction – Problems



- Indirect jumps (jump targets calculated at runtime) cannot be resolved statically in general
- Thorough code obfuscation may thwart disassembly
- Self modifying code
- x86 allows unaligned jumps 'into' an instruction

State-of-the-art disassemblers are able to successfully process compiler generated code. This includes most of the prevalent E-mail worms.

## Malicious Behavior – Example



```
ebx,ebx
                                     # clear register
xor
       eax, [ebp+ExFileName]
                                     # store address of buffer
lea
                                     # size of string buffer
       0 \times 0104
push
push
                                     # push address
       eax
       ebx
push
                                     # push a zero
call
                                     # system call
       ds:GetModuleFileNameA
       eax, [ebp+NewFileName]
                                     # store destination address
lea
push
       ebx
                                     # push a zero
                                     # push destination
push
       eax
lea
       eax, [ebp+ExFileName]
                                     # store source address
push
                                     # push source address
       eax
call
                                     # system call
       ds:CopyFileA
```

Code fragment of the Klez.h worm

#### Malicious Behavior – Characteristics



. . .

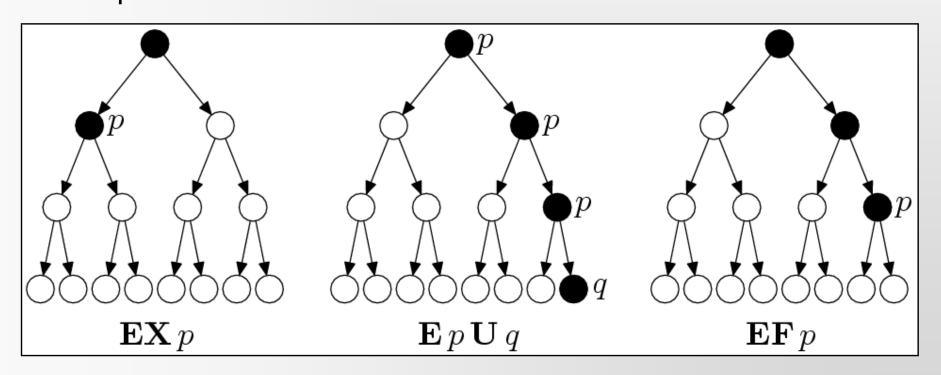
```
ebx,ebx
xor
lea
        eax, [ebp+ExFileName]
        0 \times 0104
push
push
        eax
push
        ehx
call
       ds:GetModuleFileNameA
lea
        eax, [ebp+NewFileName]
push
        ebx
push
        eax
lea
        eax, [ebp+ExFileName]
push
        eax
call
        ds:CopyFileA
```

- Temporal and functional dependencies of system calls characterize behavior
- Arbitrary order of independent instructions
- Register and variable substitution
- Flexibility and and readability of specifications

# Specifying Behavior – CTL



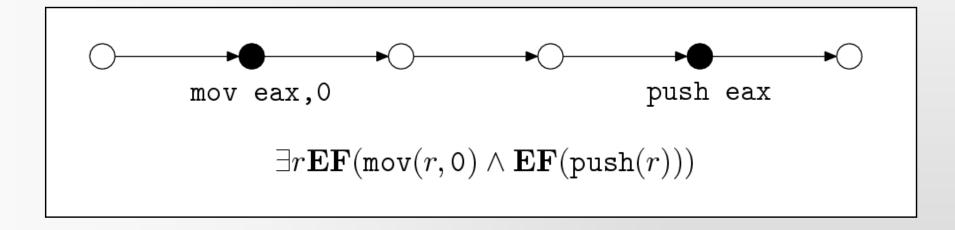
- The logic CTL allows the specification of temporal properties of systems
- Examples:



# Specifying Behavior – CTPL



 The new logic CTPL is based on CTL but allows free variables in propositions and quantifiers in formulas



Through this extension, CTPL becomes particularly useful for specifying behavior of assembler code

## **CTPL Specifications**



 Example 1: Initialize register with zero; later this register is pushed onto the stack

$$\exists r \mathbf{EF}(\mathtt{mov}(r,\mathtt{O}) \wedge \mathbf{EF}(\mathtt{push}(r)))$$

• Example 2: Same as 1, but ensure integrity of the register

$$\exists r \mathbf{EF}(\mathsf{mov}(r, 0) \land \mathbf{E}(\neg \exists t \, \mathsf{mov}(r, t) \, \mathbf{U} \, \mathsf{push}(r)))$$

## CTPL Specifications – System Calls



System call with parameter initialization:

Parameter Initialization

```
\exists L \exists r_1 ( \quad \mathbf{EF}(\mathsf{mov}(r_1,0) \wedge \mathbf{EF} \# loc(L)) \wedge \\ \exists r_2 \mathbf{EF}(\mathsf{push}(r_2) \wedge \mathbf{EF}(\mathsf{push}(r_1) \wedge \# loc(L) \wedge \mathbf{EF}(\mathsf{call}(\mathsf{func})))) \\ )
```

Stack layout, invoke system call

# CTPL Specifications – System Calls



System call with parameter initialization:

```
\exists L \exists r_1 ( \mathbf{EF}(\mathsf{mov}(r_1, 0) \land \mathbf{EF} \# loc(L)) \land \\ \exists r_2 \mathbf{EF}(\mathsf{push}(r_2) \land \mathbf{EF}(\mathsf{push}(r_1) \land \# loc(L) \land \mathbf{EF}(\mathsf{call}(\mathsf{func})))) \\ )
```

Formulas are linked by the location predicate #10c

## CTPL Specification Based on Klez



```
\exists L_m \exists L_c \exists v_{File}(
                   \exists r_0 \exists r_1 \exists L_0 \exists L_1 \exists c_0 (
                             \mathbf{EF}(\operatorname{lea}(r_0, v_{File}) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t (\operatorname{mov}(r_0, t) \vee \operatorname{lea}(r_0, t))) \mathbf{U} \# loc(L_0)) \wedge
                             \mathbf{EF}(\mathsf{mov}(r_1, 0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\mathsf{mov}(r_1, t) \lor \mathsf{lea}(r_1, t))) \mathbf{U} \# loc(L_1)) \land
                             \mathbf{EF}(\operatorname{push}(c_0) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \vee \operatorname{pop}(t)))
5.
                                       \mathbf{U}(\operatorname{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
6.
                                                 \mathbf{U}(\operatorname{push}(r_1) \land \#loc(L_1) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
                                                           \mathbf{U}(\texttt{call}(\texttt{GetModuleFileNameA}) \land \#loc(L_m)))))
8.
9.
                   \wedge (\exists r_0 \exists L_0 (
10.
                             \mathbf{EF}(\operatorname{lea}(r_0, v_{File}) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t (\operatorname{mov}(r_0, t) \vee \operatorname{lea}(r_0, t))) \mathbf{U} \# loc(L_0)) \wedge
11.
                             \mathbf{EF}(\operatorname{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
12.
13.
                                       \mathbf{U}(\text{call}(\text{CopyFileA}) \land \#loc(L_c)))
14.
15.
                   \wedge \mathbf{EF}(\#loc(L_m) \wedge \mathbf{EF} \#loc(L_c))
16.
```

## CTPL Specification Based on Klez



```
\exists L_m \exists L_c \exists v_{File}
                                                           \exists r_0 \exists r_1 \exists L_0 \exists L_1 \exists c_0 (
                                                                                        3.
                                                                                         \mathbf{EF}(\mathsf{mov}(r_1,0) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t(\mathsf{mov}(r_1,t) \vee \mathsf{lea}(r_1,t))) \mathbf{U} \# loc(L_1)) \wedge
4.
                                                                                        \mathbf{EF}(\operatorname{push}(c_0) \wedge \mathbf{EXE}(\neg \exists t(\operatorname{push}(t) \vee \operatorname{pop}(t)))
5.
                                                                                                                     \mathbf{U}(\operatorname{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
6.
                                                                                                                                                   \mathbf{U}(\operatorname{push}(r_1) \land \#loc(L_1) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
                                                                                                                                                                                 \mathbf{U}(\texttt{call}(\texttt{GetModuleFileNameA}) \land \#loc(L_m)))))
8.
9.
10.
                                                            \wedge (\exists r_0 \exists L_0 (
                                                                                        \mathbf{EF}(\mathbf{lea}(r_0, v_{File}) \wedge \mathbf{EXE}(\neg \exists t(\mathsf{mov}(r_0, t) \vee \mathbf{lea}(r_0, t))) \mathbf{U} \# loc(L_0)) \wedge \mathbf{EXE}(\mathbf{lea}(r_0, t_0)) \wedge \mathbf{EX
 11.
                                                                                        \mathbf{EF}(\mathrm{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\mathrm{push}(t) \lor \mathrm{pop}(t)))
 12.
 13.
                                                                                                                     \mathbf{U}(\text{call}(\text{CopyFileA}) \land \#loc(L_c)))
14.
 15.
                                                        \wedge \mathbf{EF}(\#loc(L_m) \wedge \mathbf{EF} \#loc(L_c))
 16.
```

## CTPL Specification Based on Klez



```
\exists L_m \exists L_c \exists v_{File}(
                   \exists r_0 \exists r_1 \exists L_0 \exists L_1 \exists c_0 (
                             \mathbf{EF}(\operatorname{lea}(r_0, v_{File}) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t (\operatorname{mov}(r_0, t) \vee \operatorname{lea}(r_0, t))) \mathbf{U} \# loc(L_0)) \wedge
                             \mathbf{EF}(\mathsf{mov}(r_1, 0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\mathsf{mov}(r_1, t) \lor \mathsf{lea}(r_1, t))) \mathbf{U} \# loc(L_1)) \land
                             \mathbf{EF}(\operatorname{push}(c_0) \wedge \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \vee \operatorname{pop}(t)))
5.
                                      \mathbf{U}(\operatorname{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
6.
                                                \mathbf{U}(\operatorname{push}(r_1) \land \#loc(L_1) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\operatorname{push}(t) \lor \operatorname{pop}(t)))
                                                          \mathbf{U}(\texttt{call}(\texttt{GetModuleFileNameA}) \land \#loc(L_m))))
8.
9.
10.
                   \wedge (\exists r_0 \exists L_0 (
                             \mathbf{EF}(\operatorname{lea}(r_0, v_{File}) \wedge \mathbf{EXE}(\neg \exists t(\operatorname{mov}(r_0, t) \vee \operatorname{lea}(r_0, t)))\mathbf{U} \# loc(L_0)) \wedge
11.
                             \mathbf{EF}(\mathrm{push}(r_0) \land \#loc(L_0) \land \mathbf{EX} \mathbf{E}(\neg \exists t(\mathrm{push}(t) \lor \mathrm{pop}(t)))
12.
                                       \mathbf{U}(\mathsf{call}(\mathsf{CopyFileA}) \land \#loc(L_c))
13.
14.
                   \wedge \mathbf{EF} \not\# loc(L_m) \wedge \mathbf{EF} \not\# loc(L_c)
15.
16.
```

# Macro-Supported CTPL



 Recurring patterns in specifications can be encapsulated by a set of macros

```
%nostack%noassign%syscall%sysfuncstack integrityvariable integritysystem callsystem call with<br/>return value
```

- Unneeded variables are replaced by wildcards
- Allows succinct and natural specifications

```
EF(
%syscall(GetModuleFileNameA, $*, $pFile, 0) &
E %noassign($pFile) U %syscall(CopyFileA, $pFile)
)
```

CTPL specification based on Klez in prototype syntax

# CTPL Model Checking Algorithm



- Based on classic explicit CTL Model Checking
  - Linear time algorithm by Clarke and Emerson
  - Bottom-up evaluation of the formula
  - Dynamic programming
- The CTPL algorithm has to collect variable bindings
- CTPL Model Checking is PSPACE-complete
- Efficient in real world settings:
  - Algorithm is exponential in size of the specification,
  - But linear in size of the model

# Experimental Results



Badtrans.a Bugbear.a Bugbear.e Dumaru.a Dumaru.b	\frac{1}{\sqrt{1}}	\frac{}{}	102.0 5.0 1.6 3.7 3.6	
Klez.a Klez.e Klez.h MyDoom.a MyDoom.i MyDoom.m NetSky.b NetSky.d NetSky.d NetSky.p Nimda.a Nimda.e			2.2 5.9 6.0 2.7 2.2 2.2 5.6 1.9 0.6 3.4 4.9	CopySelf ExecOpened Time (s)

## Summary



- Model Checking is suited for mutation tolerant detection of malware
- One specification fits a large class of worms
- Proactive detection raises skill threshold for malware writers
- Future directions:
  - Abstraction of assembler code
  - Extensible macro language
  - Efficient implementation (e.g. with OBDDs)
  - Make use of program analysis techniques (data flow, slicing, interval analysis)

# Thank you



Thank you for your attention.

Questions?